# Accelerating the Delfs–Galbraith Algorithm with Fast Subfield Root Detection

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Based on joint work with Craig Costello and Jia Shi

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#### Outline

- 1 The Supersingular Isogeny Problem
- 2 The Delfs-Galbraith Algorithm
- 3 SuperSolver: Accelerating Delfs-Galbraith's Algorithm
- Worked Example
- 6 Results and Conclusions

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### The Supersingular Isogeny Problem

In its most general form, the *supersingular isogeny problem* asks to find an isogeny

$$\phi: E_1 \to E_2$$
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The best known classical attack against this general problem is the **Delfs–Galbraith algorithm**.

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- Provide an optimised implementation of the Delfs-Galbraith algorithm: Solver.
- Develop an efficient method to detect if a polynomial  $f(X) \in \mathbb{F}_{p^d}[X]$  has a root in  $\mathbb{F}_p$ .

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- Provide an optimised implementation of the Delfs-Galbraith algorithm: Solver.
- Develop an efficient method to detect if a polynomial  $f(X) \in \mathbb{F}_{p^d}[X]$  has a root in  $\mathbb{F}_p$ .
- Use this to introduce an improved attack, SuperSolver, with lower concrete complexity.

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#### Properties:

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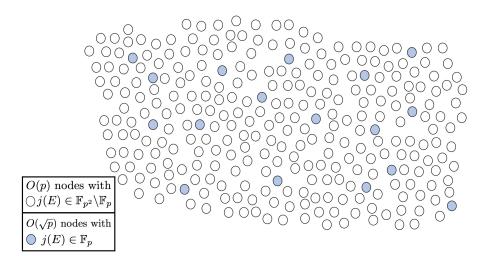
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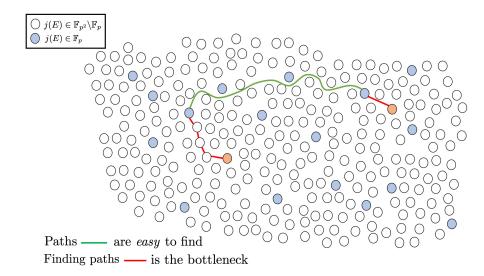
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- Ramanujan graph: rapid mixing.



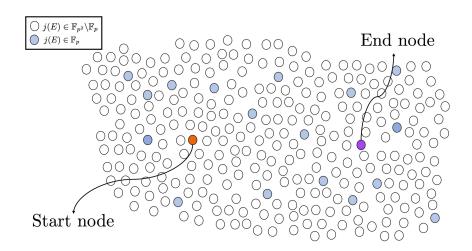
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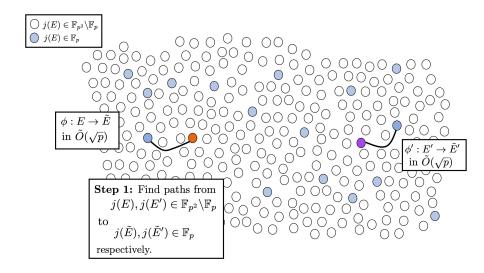
### **Key Observation**



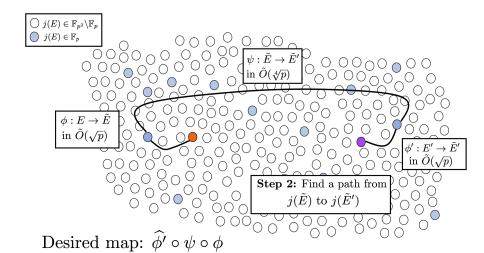
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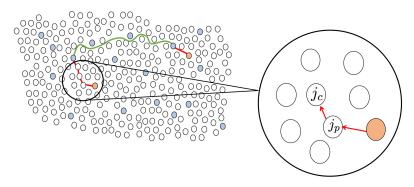
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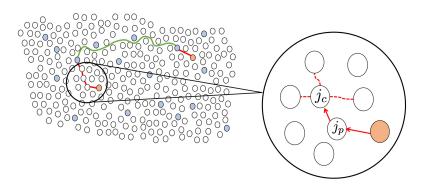
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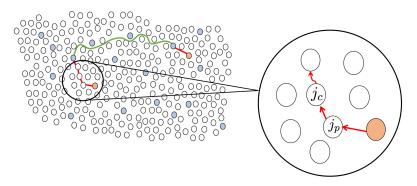
1. Store the current and previous j-invariants  $j_c$  and  $j_p$ .

Taking a self-avoiding step in  $\mathcal{X}(\bar{\mathbb{F}}_p, \ell)$ :



2. Find the  $N_{\ell}-1$  roots of  $\Phi_{\ell,p}(X,j_c)/(X-j_p)$ .

Taking a self-avoiding step in  $\mathcal{X}(\bar{\mathbb{F}}_p, \ell)$ :



3. Choose one of these and walk to the corresponding node.

# Concrete Complexity of Delfs-Galbraith

Solver is an optimised implementation of the Delfs–Galbraith algorithm with  $\ell=2$ .

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Experimentally, given a node  $j \in \mathbb{F}_{p^2} \backslash \mathbb{F}_p$ , the average number of  $\mathbb{F}_p$  multiplications needed to find a path to a node  $j' \in \mathbb{F}_p$  is

$$c \cdot \sqrt{p} \cdot \log_2 p$$
,

with  $0.75 \le c \le 1.05$ .

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### **Key Observation**

At each step, the precise values of the  $\ell$ -isogenous neighbours do not need to be known, only whether it lies in  $\mathbb{F}_p$ .

At each step of the random walk in  $\mathcal{X}(\bar{\mathbb{F}}_p,2)$ , SuperSolver inspects the  $\ell$ -isogeny graph with fast subfield root detection for  $\ell$  in a carefully chosen set, to efficiently detect whether  $j_c$  has an  $\ell$ -isogenous neighbour in  $\mathbb{F}_p$ .

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#### Lemma

Let  $\pi$  be the p-power Frobenius map and f a polynomial in  $\mathbb{F}_{p^2}[X]$ . Then,  $\gcd(f,\pi(f))$  is the largest divisor of f defined over  $\mathbb{F}_p$ . In particular, if

$$\deg\big(\gcd(f,\pi(f))\big) = \begin{cases} 1, & f \text{ has a root in } \mathbb{F}_p \\ 0, & f \text{ does not have a root in } \mathbb{F}_p \end{cases}.$$

**Problem:** In general  $f, \pi(f) \in \mathbb{F}_{p^2}[X]$  and we want to avoid costly multiplications in  $\mathbb{F}_{p^2}$ .

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#### Observation

For polynomials  $f_1, f_2 \in \mathbb{F}_{p^2}[X]$ , if

$$g_1 = \textit{af}_1 + \textit{bf}_2, \text{ and } g_2 = \textit{cf}_1 + \textit{df}_2,$$

with  $a,b,c,d\in\mathbb{F}_{p^2}$  such that  $ad-bc\neq 0$  with we have

$$\gcd(f_1,f_2)=\gcd(g_1,g_2).$$

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**Solution:** Let  $\alpha \in \mathbb{F}_{p^2}$  be such that  $\mathbb{F}_{p^2} = \mathbb{F}_p(\alpha)$ . For  $f(X) := \Phi_{\ell,p}(X,j_c)$ , if

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We can avoid **all** multiplications over  $\mathbb{F}_{p^2}$ : if we write the coefficients of f(X) as  $a_k^{(1)} + a_k^{(2)} \alpha$  (say  $\alpha^2 = -1$ ), then

$$g_1(X) = \sum_{k=0}^n a_k^{(1)} X^k$$
, and  $g_2(X) = \sum_{k=0}^n a_k^{(2)} X^k$ .

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- Find the subset of L that minimises the total cost of each step:

$$\mathsf{cost} = \frac{\mathsf{total} \ \# \ \mathsf{of} \ \mathbb{F}_{\textit{p}} \ \mathsf{multiplications}}{\mathsf{total} \ \# \ \mathsf{of} \ \mathsf{nodes} \ \mathsf{revealed}}.$$

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$$cost = \frac{total \# of \mathbb{F}_p \text{ multiplications}}{total \# of nodes revealed}.$$

Calculating the list of optimal  $\ell$ 's can be done in precomputation.

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### Sample our start and end node:

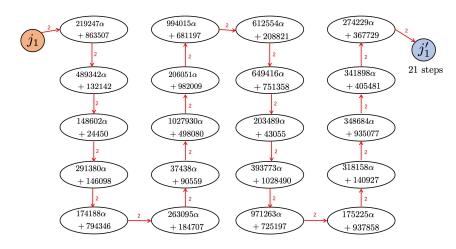
**Start Node:**  $j_1 = 129007\alpha + 818380$ 

**End Node:**  $j_2 = 97589\alpha + 660383$ 

Path from  $j_1 = 129007\alpha + 818380$  to subfield node.



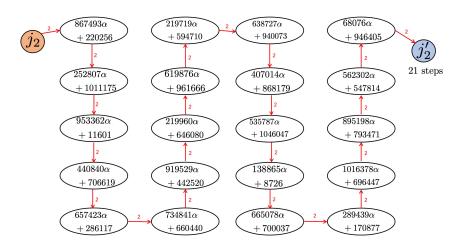
Path from  $j_1 = 129007\alpha + 818380$  to subfield node  $j'_1 = 760776$ .



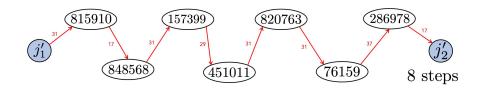
Path from  $j_2 = 97589\alpha + 660383$  to subfield node.



Path from  $j_2 = 97589\alpha + 660383$  to subfield node  $j'_2 = 35387$ .



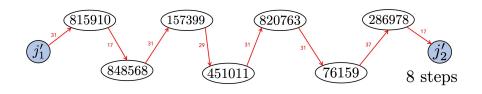
Path between subfield nodes  $j'_1 = 760776$  and  $j'_2 = 35387$ .



We take steps in  $\mathcal{X}(\bar{\mathbb{F}}_p, \ell)$  with  $\ell \in \{17, 29, 31, 37\}$ .

### Worked Example: Solver

Path between subfield nodes  $j'_1 = 760776$  and  $j'_2 = 35387$ .



We take steps in  $\mathcal{X}(\bar{\mathbb{F}}_p, \ell)$  with  $\ell \in \{17, 29, 31, 37\}$ .

In total, the path has 21 + 21 + 8 = 50 steps.

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The list of optimal  $\ell$ 's is precomputed as  $L=\{3,5\}$ . Path from  $j_1=129007\alpha+818380$  to subfield node  $j_1'=35387$ .



$$\Phi_{3,p}(X, 219247\alpha + 863507) = X^4 + (212814\alpha + 479338)X^3 + (408250\alpha + 920025)X^2 + (811739\alpha + 93038)X + 942336\alpha + 847782$$

The list of optimal  $\ell$ 's is precomputed as  $L=\{3,5\}$ . Path from  $j_1=129007\alpha+818380$  to subfield node  $j_1'=35387$ .



$$g_1 = X^4 + 479338X^3 + 920025X^2 + 93038X + 847782$$
  
 $g_2 = 425628X^3 + 816500X^2 + 574905X + 836099$ 

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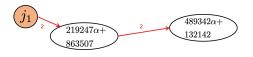
$$\gcd(g_1,g_2)=1 \Longrightarrow$$
 no 3-isogenous neighbour in  $\mathbb{F}_p$ 

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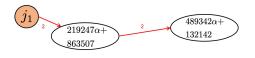


3-isogenous neighbour in  $\mathbb{F}_p$ ? No. Similarly, no 5-isogenous neighbour in  $\mathbb{F}_p$ .

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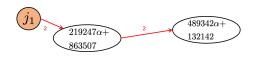


The list of optimal  $\ell$ 's is precomputed as  $L=\{3,5\}$ . Path from  $j_1=129007\alpha+818380$  to subfield node  $j_1'=35387$ .



$$\Phi_{3,p}(X,489342\alpha+132142) = X^4 + (872004\alpha+13960)X^3 + (1031755\alpha+822066)X^2 + (969683\alpha+747785)X + 813010\alpha+255391.$$

The list of optimal  $\ell$ 's is precomputed as  $L=\{3,5\}$ . Path from  $j_1=129007\alpha+818380$  to subfield node  $j_1'=35387$ .



$$g_1 = X^4 + 13960X^3 + 822066X^2 + 747785X + 255391$$
  

$$g_2 = 695435X^3 + 1014937X^2 + 890793X + 577447$$

$$\gcd(g_1,g_2) = X + 1013186 \Longrightarrow \text{ 3-isogenous neighbour in } \mathbb{F}_p$$
$$-1013186 = 35387$$

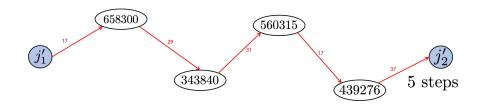
The list of optimal  $\ell$ 's is precomputed as  $L = \{3, 5\}$ . Path from  $j_1 = 129007\alpha + 818380$  to subfield node  $j_1' = 35387$ .



The list of optimal  $\ell$ 's is precomputed as  $L=\{3,5\}$ . Path from  $j_2=97589\alpha+660383$  to subfield node  $j_2'=292917$ .

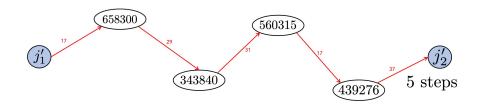


The list of optimal  $\ell$ 's is precomputed as  $L=\{3,5\}$ . Path between subfield nodes  $j_1'=35387$  and  $j_2'=292917$ .



We take steps in  $\mathcal{X}(\bar{\mathbb{F}}_p, \ell)$  with  $\ell \in \{17, 29, 31, 37\}$ .

The list of optimal  $\ell$ 's is precomputed as  $L=\{3,5\}$ . Path between subfield nodes  $j_1'=35387$  and  $j_2'=292917$ .



We take steps in  $\mathcal{X}(\bar{\mathbb{F}}_p, \ell)$  with  $\ell \in \{17, 29, 31, 37\}$ .

In total, the path has 3 + 3 + 5 = 11 steps.

### Outline

- The Supersingular Isogeny Problem
- 2 The Delfs-Galbraith Algorithm
- SuperSolver: Accelerating Delfs—Galbraith's Algorithm
- 4 Worked Example
- 5 Results and Conclusions

Experiments on small primes and many j-invariants.

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**Example:** For  $p = 2^{24} - 3$ , averaging over 5000 pseudo-random supersingular j-invarants in  $\mathbb{F}_{p^2}$ , we get:

Solver used  $112878 \mathbb{F}_p$  multiplications and walked on 1897 nodes.

SuperSolver used 53900  $\mathbb{F}_p$  multiplications and walked on 318 nodes.

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Experiments on cryptographic sized primes and one j-invariant. We ran SuperSolver and Solver until the number of  $\mathbb{F}_p$  multiplications used exceeded  $10^8$ , recording the total number of nodes covered.

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### **Examples:**

For  $p = 2^{50} - 27$ , SuperSolver covers between 3 and 4 times the number of nodes that Solver does.

For  $p = 2^{800} - 105$ , SuperSolver covers between 18 and 19 times the number of nodes.

#### Conclusions

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- We improve the concrete complexity of Delfs–Galbraith asymptotic complexity is unchanged.
- No direct impact on SIDH and SIKE there are faster claw-finding algorithms.
- Affects other proposals, such as B-SIDH and SQISign, with Delfs-Galbraith as their best attack.

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• Can we combine  $\Phi_m(X,j)$  and  $\Phi_n(X,j)$  so that we can detect whether j has an nm-isogenous neighbour doing operations with  $\Phi_m$  and  $\Phi_n$  only?

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- What does a quantum version of SuperSolver look like?
- Other applications of subfield detection